# Analytical solution of the transport equation for exponentially decreasing initial concentration in shallow water table condition in an irrigated field

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Abstract

Most of the agricultural activities are limited for the depth of 15 – 20 cm and rest soil remain enact for long periods which inhibits the microbial activities below this depths and create an initial concentration of nutrients exponentially decreasing with depth. An attempt has been made to develop analytical models for time-dependent nitrification/ denitrification and depth-dependent absorption of urea fertilizer in high water table conditions with fertigation. Laplace transformation method was used to solve the unsteady-state advection-dispersion equation. The analytical solutions that can be derived by this method assist understanding of the movement of fertilizer in irrigated fields. The developed models were validated with the experimental results. They were closely predicting the fertilizer movement in one-dimension soil medium. The little deviation of result from observed values may be due to change of dispersion coefficient and velocity with moisture content. Here these parameters were assumed as constant throughout the time under consideration. Models developed for constant degradation rate is predicting very close to observe values which shows that the soil under study has no depth-dependent degradation. The developed models may be helpful for the planning of drain design, nutrient management and assessment of potential hazards to groundwater in agricultural fields by the knowledge of exact transport parameters and boundary conditions universally.

#### Introduction

The topsoil up to a depth of 15-20 cm supports most of the seasonal and shallow deeprooted cereals crops. These types of crops may be grown successfully without tillage in a wide range of soil. The popularity of zero-till machines in Indian agriculture avoids the tillage of soil up to a great extent. Addition of different biofertilizers and soil ameliorators increase the biological activities in upper soil and leave the lower soil enact and creates the situation of exponentially decreasing initial concentration of different soil nutrients in soil mass in high water table areas. Mathematical modelling of processes, in the unsaturated zone, is useful for the agricultural management of cultivated sites, for prediction of the fate of agrochemicals, and assessment of the potential hazard of shallow groundwater contamination. The difficulty of solving the transport equation in the unsaturated zone relies on its strong nonlinearity. Although significant efforts have been made to overcome the mathematical difficulties, most analytical solutions are derived for one-dimensional vertical transport under various simplifying assumptions. Accounting for the spatial heterogeneity of natural soils renders the transport problem even more complicated.

Bresler and Laufer (1974) simulated the movement of nitrate inhomogeneous soil profile in the presence of NO<sub>3</sub>-N production (nitrification). Sexton et al. (1977) modelled nitratenitrogen movement and dissipation in fertilized agricultural lands but did not include representation of any other fertilizer from nitrogen. Wagenet et al. (1977) extended the mathematical analysis of Cho (1971) and Misra et al. (1974) to describe the transport and transformation of urea, ammonium nitrogen and nitrate nitrogen soil profile as a function of depth and time subject to either steady or pulse feed application of nitrogen, and validated with controlled laboratory experiments.

Davidson et al. (1978) developed research and development type models on the fate of nitrogen in the root zone by simplifying assumptions of water and solute processes in the field. Watts and Hanks (1978), Tillotson et al (1980), Tillotson and Wagenet (1982) developed a model that simulated most of the major transformations of the nitrate as well as the uptake by the crop, but fell short of fully describing the system in the plant growth and yield response. Selim and Iskander (1981) developed the model for calculating pollution from organic wastes and excessive fertilization. Tanji et al. (1982) presented a steady-state nitrogen model developed on a mass balance approach, which considered water and nitrogen flow on an annual or cropped cycle time basis. Barraclough (1989), Borg et al. (1990), Benbi et al. (1991), Carbon et al. (1991) also developed soil water, nitrogen models. Izadi et al. (1996) combined functional sub-model and analytical solution to the steady-state convection dispersion equations to predict the nitrate concentration in the root zone. Lessoff and Indelman (2004) investigated the penetration of reactive solute into a soil during a cycle of water infiltration and redistribution by deriving analytical closed-form solutions for fluid flux, moisture content and contaminant concentration Sander and Braddock (2005) presented a range of analytical solutions to the combined transient water and solute transport for horizontal flow. Smedt (2007) reported an analytical solution and analysis of solute transport in rivers affected by diffusive transfer in the hyporheic zone. Khakpour and Kambiz (2008) reported an analytical solution of transport phenomena within the PEM fuel cell. Zhan et al (2009) deduced an analytical solution of two-dimensional solute transport in an aquifer—aquitard system. Srinivasan and Clement (2008) reported analytical solutions for sequentially coupled one-dimensional reactive transport problems. Sadek (2009) compared the various available analytical solution with numerical methods is deduced that the analytical solution may be used as a versatile tool for assessment of contaminant transport. Jozse and Janos (2009) derived an analytical solution of the coupled 2-D turbulent heat and vapour transport equations and the complementary relationship of evaporation. Guerrero and Skaggs (2010) presented a general analytical solution for one-dimensional advection-dispersion equation with distance-dependent coefficients. An integrating factor was employed to obtain a transport equation that has a self-adjoint differential operator, and a solution was found using the generalized integral transform technique.

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The mechanisms of solute transport in the irrigated field are significantly influenced by attenuation processes such as adsorption and nitrification/denitrification processes. Most of the available analytical solutions are based on linear equilibrium adsorption and first-order nitrification and possibly zeroth-order production (*van Genuchten* and *Alves* (1982) for several analytical solutions). Here the movement of urea fertilizer was analytically solved under depth-dependent adsorption factor and combination of constant and exponential nitrification/denitrification rate for exponentially decreasing initial condition. Following assumptions were considered for formulating the boundary value problems:

- 1. The soil is unconfined, homogeneous and isotropic overlying an impermeable layer which is having water table depth H meter from the soil surface,
- 2. The water through deep percolation moves vertically downward until it joins the groundwater,

- 97 3. Darcy and Fick's laws hold good,
- 98 4. The fluid is of constant density and viscosity,
- In the present study 1-D, Richard's equation in combination with solute transport equation, which incorporates nitrification and de-nitrification, and depth-dependent soil
- and water matrix factor was used to characterize the movement of applied fertilizer in
- irrigated agriculture having shallow water table conditions.

## **Governing Equation**

104 Transport equation in the unsaturated porous medium is given by:

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$$\frac{\partial}{\partial t} (\theta C + \rho S) = \frac{\partial}{\partial z} \left( \theta D \frac{\partial C}{\partial z} - qC \right) - \alpha \theta C - \rho \beta C \mp \gamma \theta \qquad \dots (1)$$

- where C = C(z, t) is the concentration of chemical in the liquid phase in mg/l, S =
- S (z, t) is the concentration of chemical in the solid phase in mg/l, D = D(z, t) is the
- dispersion coefficient in m<sup>2</sup>/day,  $\theta = \theta$  (z, t) is the volumetric water content cm<sup>3</sup>
- 110 /cm<sup>3</sup>, q = q(z, t) is the flux of water in m/day,  $\rho = \rho$  (z) is the soil bulk density
- 111 in gm/cm³,  $\alpha = \alpha$  (z) is the first-order degradation rate constant in the liquid
- phase,  $\beta = \beta$  (z) is the first-order degradation rate constant in the solid phase,
- 113  $\gamma = \gamma$  (z) is the zero-order production rate constant in the liquid phase.
- 114 Here  $\alpha$ ,  $\beta$   $\gamma$  and are zero or greater.
- 115 Considering that soil medium remains intact with time, and introducing mass balance
- equation for one-dimensional unsteady unsaturated flow condition as given by Chow et
- 117 al. (1988), Eqn. (1) reduces to:

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$$\frac{\partial C}{\partial t} = D \frac{\partial^2 C}{\partial z^2} - v \frac{\partial C}{\partial z} - RC \mp \gamma \qquad \dots (2)$$

- 120 where  $v = q/\theta R = \left(\alpha + \frac{\rho\beta}{\theta}\right)$  and, the factor representing the combined effect of liquid
- and solid phase degradation rate. Here we assume  $R(C) = R_o b (C_o C)$  where  $R_o$
- represents potential degradation rate at the land surface; b is reduction factor due to
- which degradation decreases linearly as the depth from the land surface it increases up to
- 124 a specific value; and C<sub>o</sub> is initial concentration at the ground surface. For the
- development of the model, the combination of constant and exponentially decreasing
- nitrification/de-nitrification rate which may be given as  $\gamma(t) = \gamma_0 + \gamma_1 e^{-rt}$ , where  $\gamma_0 \gamma_1$  and
- are constant nitrification/de-nitrification rates, r is decay constant and t represents time.

- 129 The initial and boundary conditions in mathematical terms, for the solute flow problem in
- the unsaturated zone under the above situation, may be written as:

$$C(z,o) = C_z(z,o) \qquad \text{at } t = o \qquad \text{for } o < z < H$$

$$131 \qquad C(o,t) = C_1 \qquad \text{at } t > o \qquad \text{for } z = o$$

$$C(H,t) = C_2 \qquad \text{at } t > o \qquad \text{for } z = H$$

- where  $C_1 = g_1 e^{-h t}$ ,  $C_2 = g e^{h t}$ ,  $g_1$  and g are the concentrations at the ground surface and H
- meter below the soil surface before application of fertigation.  $C_z(z,0)$  is the distribution
- of initial concentration in the porous medium. Devising a transform given by Eqn. (4)
- 135 converted the Eqn. (2) and Eqn. (3) into standard heat flow equation and given by Eqn (5)
- and Eqn(6), respectively.

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$$C(z,t) = V(z,t) \exp\left(\frac{vz}{2D} - \left(\frac{v^2}{4D} + b\right)t\right) + \frac{\gamma_1 e^{-rt}}{b-r} + \frac{\gamma_0 + bC_0 - R_0}{b}$$
 ...(4)

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$$\frac{\partial^2 V}{\partial z^2} = \frac{1}{D} \frac{\partial V}{\partial t}$$
 ...(5)

$$V(z,0) = (C_z - A - B)e^{-az} = f(z)$$

$$V(0,t) = (C_1 - A - Be^{-rt})e^{dt} = f_1(t)$$

$$V(H,t) = E(C_2 - A - Be^{-rt})e^{dt} = f_2(t)$$
...(6)

141 where, 
$$A = \frac{\gamma_0 + bC_0 - R_0}{b} d = \frac{v^2}{4D} + b a = \frac{v}{2D} E = e^{-aH}$$
 and  $B = \frac{\gamma_1}{b-r}$ 

- 143 The general solution of transformed Eqn (5) under initial and boundary condition Eqn(6)
- is given by Carslaw and Jaeger (1959) and Ozisik (1980) as below:

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$$V(z,t) = \frac{2}{H} \sum_{m=1}^{\infty} e^{-D\beta_m^2 t} \sin \beta_m z \left[ \int_{0}^{H} f(z) \sin \beta_m z \, dz \right] + \left( 1 - \frac{z}{H} \right) f_1(t) + \frac{z}{H} f_2(t)$$

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$$-\frac{2}{H} \sum_{m=1}^{\infty} \frac{\sin \beta_m z}{\beta_m} \left[ f_1(0) e^{-D\beta_m^2 t} + \int_0^t e^{-D\beta_m^2 (t+\tau)} df_1(\tau) \right]$$

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$$+\frac{2}{H}\sum_{m=1}^{\infty}(-1)^{m}\frac{\sin\beta_{m}z}{\beta_{m}}\left[f_{2}(0)e^{-D\beta_{m}^{2}t}+\int_{0}^{t}e^{-D\beta_{m}^{2}(t+\tau)}df_{2}(\tau)\right]$$
 ...(7)

where  $\beta_m$  is the root of  $\sin \beta_m H = 0$  and  $\tau$  is a dummy variable. The solution of the

149 transport equation was obtained for exponentially decreasing initial concentration of

nitrogen in soil profile with the help of equation (7) and transformed initial and boundary

151 conditions. When  $C_z = p - e^{kz}$  i.e. exponentially decreasing with depth, then the final

solution of Eqn. (7) takes the following form:

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$$C(z,t) = \frac{2}{H} e^{az-dt} \sum_{m=1}^{\infty} A_2 \sin \beta_m z \left[ (p-A-B) \frac{\beta_m}{a^2 + \beta_m^2} \left[ 1 - (-1)^m E \right] \right]$$

$$-\frac{2}{H}e^{az-dt}\sum_{m=1}^{\infty}A_{2}\sin\beta_{m}z\ \frac{\beta_{m}}{(k-a)^{2}+\beta_{m}^{2}}\left[1-(-1)^{m}Ee^{kH}\right]$$

$$+ \left(1 - \frac{z}{H}\right) \left(C_1 - A - Be^{-rt}\right) e^{az} + \frac{z}{H} \left(C_2 - A - Be^{-rt}\right) e^{a(z-H)}$$

$$-\frac{2}{H}e^{az-dt}\sum_{m=1}^{\infty}\frac{\sin\beta_{m}z}{\beta_{m}}\left[\left(g_{1}-A-B\right)A_{2}\right]$$

$$-\frac{2}{H}e^{az-dt}\sum_{m=1}^{\infty}A_{2}\frac{\sin\beta_{m}z}{\beta_{m}}\left[\frac{A_{6}A_{2}}{s}\left(e^{-st}-1\right)\frac{A_{4}A_{2}}{K}\left(e^{-Kt}-1\right)-\frac{A_{2}B_{1}}{N}\left(e^{-Nt}-1\right)\right]$$

$$+ \frac{2}{H} e^{az-dt} \sum_{m=1}^{\infty} (-1)^m A_2 \frac{\sin \beta_m z}{\beta_m} [(g-A-B)E] + A + Be^{-rt}$$

$$159 + \frac{2}{H}e^{az-dt}\sum_{m=1}^{\infty} (-1)^m A_2 E \frac{\sin\beta_m z}{\beta_m} \frac{A_3}{l} (e^{-lt} - 1) - \frac{B_1}{N} (e^{-Nt} - 1) - \frac{A_4}{K} (e^{-Kt} - 1) \qquad \dots (8)$$

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$$A_2 = e^{-D\beta_m^2 t}$$
  $A_3 = (h+d)g$   $A_4 = d A A_5 = (C_0 - A - B)$ 

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$$A_5 = (C_0 - A - B)$$
  $A_6 = g_1(d - h),$   $B_1 = B(d - r)$ 

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$$K = D\beta_m^2 t + d$$
,  $s = D\beta_m^2 t + d - h$   $l = D\beta_m^2 t + d + h$   $N = D\beta_m^2 t + d - r$ ,

- When degradation is constant with depth i.e. b=0 Eqn (8) become imperative so for this
- situation another transformation equation (Eqn.9) was devised to transform the original
- problem into standard heat flow equation and given as

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$$C(z,t) = V(z,t) \exp\left(\frac{vz}{2D} - \left(\frac{v^2}{4D}\right)t\right) + \frac{\gamma_1 e^{-rt}}{r} + (\gamma_0 + R_0)t$$
 ...(9)

- 167 This transformation Eqn. (9) transform the problem into a simple heat flow equation
- under a constant degradation rate and gave the final solution of the problem as:

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$$C(z,t) = \frac{2}{H} e^{az-d_1t} \sum_{m=1}^{\infty} A_2 \sin \beta_m z (p-B_2) \frac{\beta_m}{a^2 + \beta_m^2} \left[ 1 - (-1)^m E \right]$$

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$$-\frac{2}{H}e^{az-d_1t}\sum_{m=1}^{\infty}A_2\sin\beta_mz\frac{\beta_m}{(k-a)^2+\beta_m^2}\left[1-(-1)^mEe^{kH}\right]$$

$$+ \left(1 - \frac{z}{H}\right) \left(C_1 - A_1 - B_2 e^{-rt}\right) e^{az} + E \cdot \frac{z}{H} \left(C_2 - A_1 - B_2 e^{-rt}\right) e^{az}$$

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$$-\frac{2}{H}e^{az-d_1t}\sum_{m=1}^{\infty}\frac{\sin\beta_mz}{\beta_m}(g_1-B_2)A_2+B_2+A_1t$$

$$-\frac{2}{H}e^{az-d_{1}t}\sum_{m=1}^{\infty}\frac{\sin\beta_{m}z}{\beta_{m}}A_{2}\begin{bmatrix} \frac{A_{7}(e^{S_{1}t}-1)}{S_{1}} - \frac{B_{3}(e^{N_{1}t}-1)}{N_{1}} - \frac{A_{1}(e^{K_{1}t}-1)}{K_{1}} \\ -\frac{A_{8}}{K_{1}^{2}} + \frac{A_{8}e^{K_{1}t}}{K_{1}^{2}} - \frac{A_{8}te^{K_{1}t}}{K_{1}} \end{bmatrix}$$

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$$+ \frac{2}{H} e^{az-d_1t} \sum_{m=1}^{\infty} (-1)^m \frac{\sin \beta_m z}{\beta_m} (g - B_2) E A_2$$

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$$+ \frac{2}{H} e^{az-d_1t} \sum_{m=1}^{\infty} (-1)^m \frac{\sin \beta_m z}{\beta_m} A_2 E \begin{bmatrix} \frac{A_9(e^{-Mt} -) - B_3(e^{-N_1} - 1)}{M} - \frac{B_3(e^{-N_1} - 1)}{N_1} - \frac{A_1(e^{K_1t} - 1)}{K_1} \\ - \frac{A_8}{K_1^2} + \frac{A_8 e^{K_1t}}{K_1^2} - \frac{A_8 t e^{K_1t}}{K_1} \end{bmatrix} ...(10)$$

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$$A_1 = (\gamma_0 + R_0), \qquad A_7 = g_1(d_1 - k) \qquad B_3 = B_2(d_1 - r) \qquad A_8 = A_1 d_1$$

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$$A_{1} = (\gamma_{0} + R_{0}),$$
  $A_{7} = g_{1}(d_{1} - k)$   $B_{3} = B_{2}(d_{1} - r)$   $A_{8} = A_{1}d_{1}$ 

177  $B_{2} = \frac{\gamma_{1}}{r}$   $d_{1} = \frac{v^{2}}{4D}$   $S_{1} = D\beta_{m}^{2} + d_{1} - k,$   $K_{1} = D\beta_{m}^{2} + d_{1}$ 

178 
$$N_1 = D\beta_m^2 + d_1 - r$$
  $M = D\beta_m^2 + d_1 + k$ 

- 179 Equation (8) and equation (10) give the complete solution of transport equation (2) under
- 180 constant and depth-dependent degradation rate for the combination of constant and
- 181 exponentially denitrification rate. In further analysis, they would be treated as Model 1
- 182 and Model 2, respectively.
- 183 **Experimental plot:** The size of the experimental plot was 5 m x 5 m, surrounded by 1-
- meter buffer zone earlier used by Behera (2003), and Garg et al. (2005) and lined by a 184
- galvanized iron sheet as discussed by Jaynes et al. (1992). The line of tensiometers and 185
- soil-water samplers were put 1.5 away from the side boundary, double ring infiltrometer 186
- 187 was kept at the centre of the plot while access tubes were installed on the centre line of
- 188 the plot. Depth of both tensiometers and samplers were kept 15, 30, 50, 75, 100 and 150
- 189 cm below the ground surface. First and sixth were installed 50 cm away from the

boundary and the distance between two were kept 80 cm. access tubes were installed 125 cm from the boundary. Observation wells were installed at two corners diagonally, keeping in mind the general flow direction of water movement. All soil water samplers were connected by a lateral line through HDPP (high-density polyvinyl pipe) and connected to a vacuum pump which creates suction and pressure in a sampler for collection of leachate sample.

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**Collection of field data**: Nitrogen solution of 448 ppm concentration, representing the nitrogen dose of 334 N kg/ ha, was applied in the experimental plot instantaneously to simulate the fertigation. Leachate samples were collected with the help of soil-water sampler and vacuum pump. Collected samples were brought to the laboratory and analyzed for total nitrogen content with the help of *Kjeldahl* unit.

## **Result and Discussion**

## Verification of the analytical solution with experimental

Physical, chemical, textural and transport parameters, required to validate the developed models, were obtained by standard methods. Computer programmes for model-1 and model-2 were developed in C++ language with defining the all input parameters in the programme except space and time. Just by giving the value of space and time one can get the concentration of fertilizer at that space and time. Performance of developed models was compared with experimental results and shown in Fig.-1 to Fig.13. First 6 figures are showing the performance of developed models at 0.15 m, 0.30 m, 0.50 m, 0.75 m, 1.00 m and 1.50 m respectively. At 0.15 m first, four days both model-1 and model-2 were over predicting a little more than observed value but from the third day onwards both predicted very close to the observed values which may be seen in Fig.1. Similar performance of models was also observed for other depths except for 1.5 m and is depictured in Fig.-2 to Fig.-5 that may be due to preferential flow (funnelling, fingering and channelling) of water through the soil or highly disturbed upper soil layer during the installation of soil-water sampler or combination of these two. Similar performance of models was also depictured in Fig.-7 to Fig.-13 at a different day and further validated their performance. Table 1 shows the per cent deviation of concentration predicted by developed models and observed values. The deviation is very less except for the first two days.

Table-5: Observed and predicted concentration (ppm) by equation 8 and equation 10

Time(days)	Model1	Model 2	Observed	% deviation	% deviation
1	409.46	395.2	375	9.19	5.39
2	470.26	464.23	451	4.27	2.93
3	481.4	477.44	473	1.78	0.94
4	483.73	480.1	478	1.20	0.44
5	484.34	480.76	481	0.69	-0.05
7	484.84	480.83	482	0.59	-0.24
10	485.64	480.73	483	0.55	-0.47

225 Analytical solutions are given by Eqns. (8) and (10) under different conditions can be 226 used to obtain the following analytical solutions as special cases: (1) Analytical solutions when the nitrification rate is constant by substituting  $\gamma_1 = 0$  in the above equations. 227 228 Graphical comparison of developed models with observed value for this condition is 229 shown in Fig- 14 to Fig- 26. (2) Analytical solutions when the nitrification rate is exponentially decreasing by substituting  $\gamma_0 = 0$  in the above equations. Graphical 230 231 comparison of developed models with observed value for this condition is shown in Fig-232 27 to Fig- 39. (3) Analytical solutions when there is no nitrification by substituting  $\gamma_0$  and  $\gamma_1 = 0$  in the above equations. Graphical comparison of developed models with 233 observed value for this condition is shown in Fig- 39 to Fig- 52 and (4) Analytical 234 solutions for non-absorbing solutes by substituting  $R_0$  and b = 0 in the above equations. 235 236 Variations in concentrations under limiting conditions were negligible for model 2 as 237 compared to model 1 in similar situations. Model-2 performed better than Model-1 at

each day. Hence it may be concluded that the under local soil condition there is no

degradation with depth for nitrogen concentration in shallow groundwater table

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#### Conclusion

condition.

Developed models would be successfully used for the prediction of fertilizer movement in the irrigated field where the water table is high with the accurate knowledge of local transport parameters. Deviation in observed and predicted concentrations were highest on the first day and decreases continuously as time passes this may be due to the highly disturbed top layer caused due to installation of instruments and G.I. sheet. Hence, the preferential flow of solute must be minimized before taking the actual observation to avoid such an outcome.

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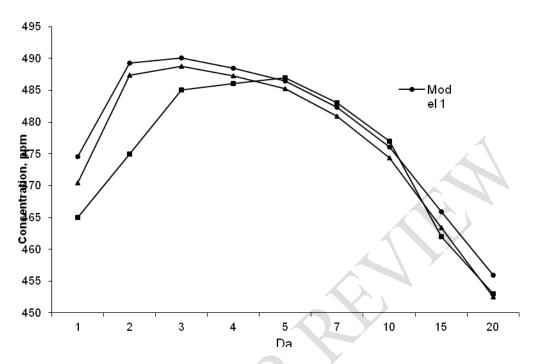


Fig.1: Performance of developed models at different days at 15 cm depth

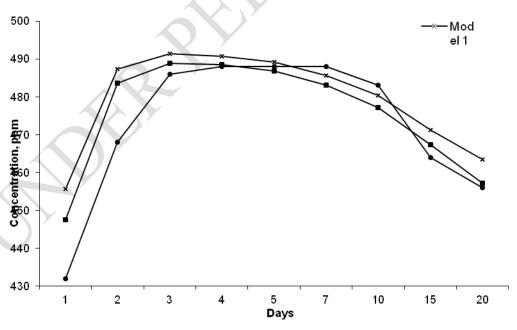
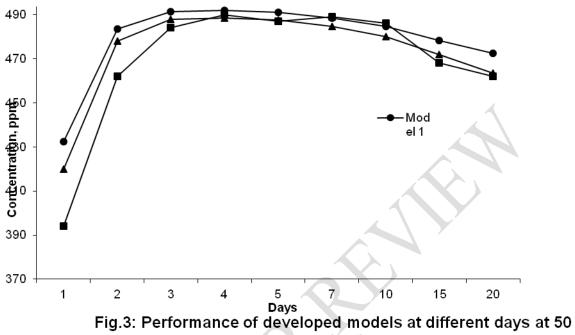


Fig.2: Performance of developed models at different days at 30 cm depth



cm depth

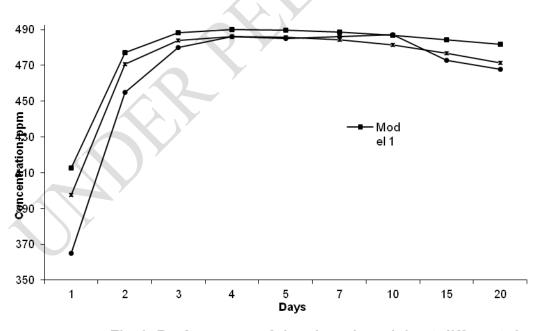


Fig.4: Performance of developed models at different days at 75 cm depth

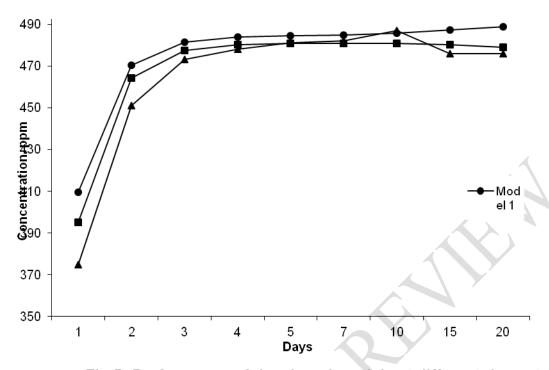


Fig.5: Performance of developed models at different days at 100 cm depth

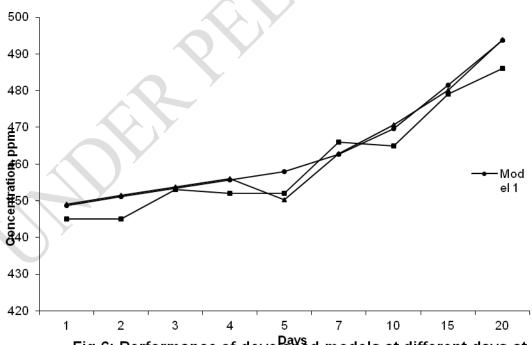


Fig.6: Performance of developed models at different days at 150 cm depth

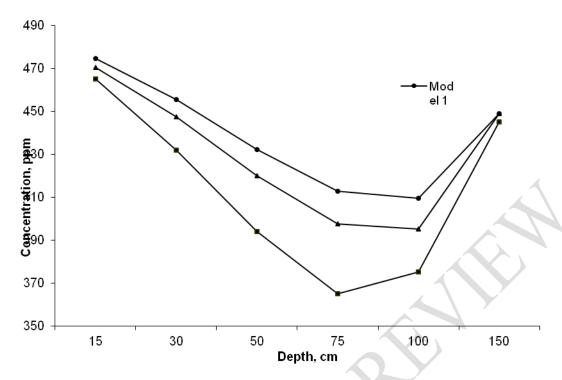


Fig. 7: Performance of developed models at different depth on first day

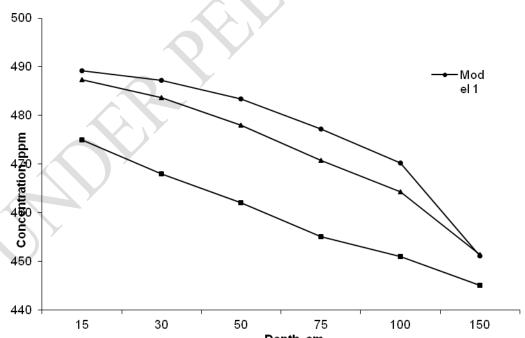


Fig. 8: Performance of developed models at different depth on second day

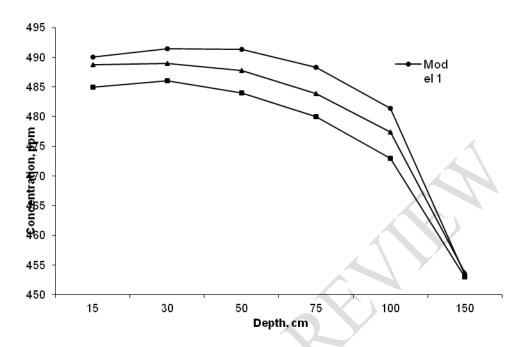


Fig.9: Performance of developed models at different depth on third day

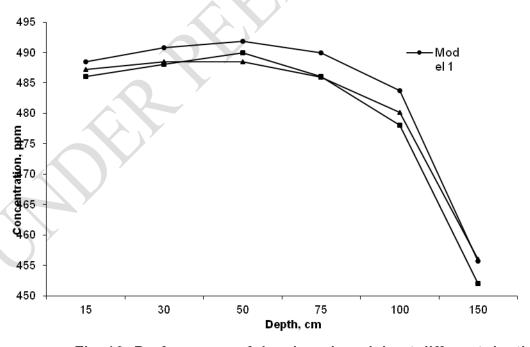


Fig. 10: Performance of developed models at different depth on fourth day

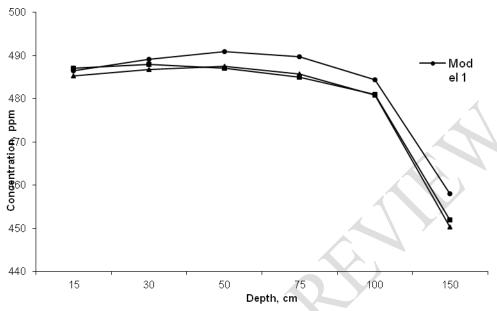


Fig. 11: Performance of developed models at different depth on fifth day

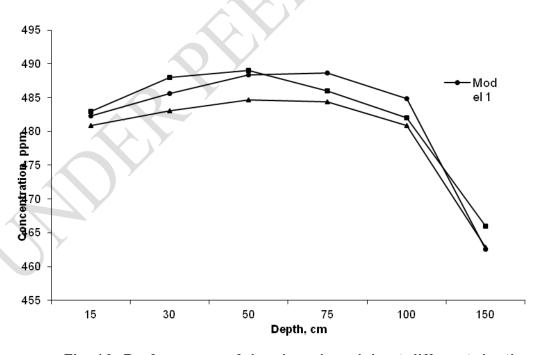


Fig. 12: Performance of developed models at different depth on seventh day

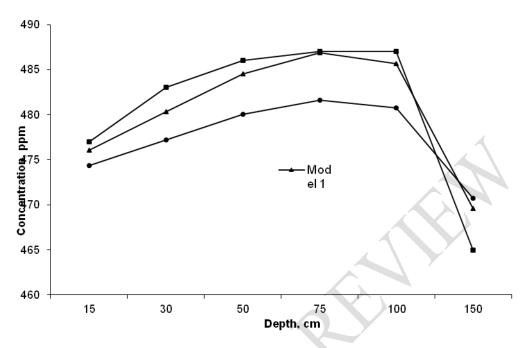


Fig. 13: Performance of developed models at different depth on tenth day

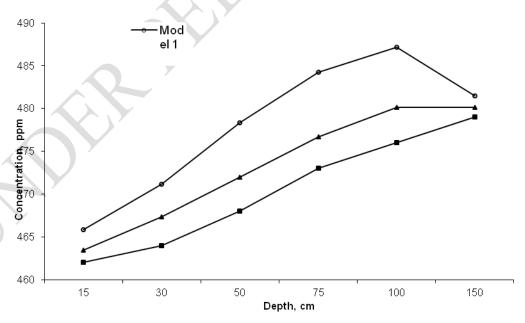


Fig. 14: Performance of developed models at different depth on fifteenth day

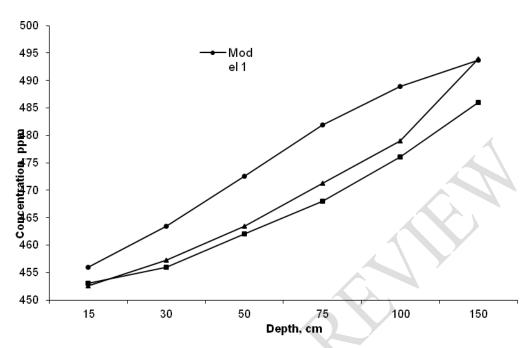


Fig.15: Performance of developed models at different depth on twenth day

001					
362					
363	at .15	meter depth			
364		1 2 obser	one	model 1	model2observed
365	1	474.56 470.43 465	15	474.56 470.43	3 465
366	2	489.23 487.33 475	30	455.6 447.55	5 432
367	3	490.07 488.733	485	50 432.33	3 419.96 394
368	4	488.51 487.25 486	75	412.81 397.56	5 365
369	5	486.49 485.21 487	100	409.46 395.2	375
370	7	482.29 480.88 483	150	448.77 449	445
371	10	476.04 474.34 477	two	)	
372	15	465.86 463.44 462	15	489.23 487.33	3 475
373	20	455.96 452.55 453	30	487.26 483.66	5 468
374		<i>y</i>	50	483.35 477.97	7 462
375	at .30	meter depth		75	477.22 470.71 455
376		1 5 obser	100	470.26 464.23	3 451
377	1	455.6 447.55 432	150	451.15 451.41	1 445
378	2	487.26 483.66 468	thre	ee	
379	3	491.4 488.92 486	15	490.07 488.73	33 485
380	4	490.74 488.43 488	30	491.4 488.92	2 486
381	5	489.16 486.81 488	50	491.37 487.75	5 484
382	7	485.63 483.04 488	75	488.28 483.93	3 480
383	10	480.34 477.22 483	100	481.4 477.44	1 473

```
384
       15
             471.16 467.33 464
                                          150
                                                 453.44 453.69 453
385
       20
              463.47 457.22 456
386
                                          four
387
                                          15
                                                 488.51 487.25 486
388
       at .5 meter depth
                                                        30
                                                               490.74 488.43 488
389
                                         50
                                                 491.86 488.52 490
              1
                     5
                            obser
390
             432.33 419.96 394
                                          75
                                                 489.92 485.99 486
       1
391
       2
             483.35 477.97 462
                                          100
                                                483.73 480.1 478
392
                                          150
       3
             491.37 487.75 484
                                                 455.71 455.98 452
393
       4
             491.86 488.52 490
394
       5
             490.89 487.5 487
                                          five
395
       7
             488.36 484.63 489
                                                 486.49 485.21 487
                                          15
396
       10
             484.52 480.02 486
                                          30
                                                 489.16 486.81 488
397
       15
             478.37 471.97 468
                                          50
                                                 490.89 487.5 487
398
       20
             472.5 463.46 462
                                          75
                                                 489.74 485.76 485
399
                                          100
                                                 484.34 480.76 481
400
       at .75 meter depth
                                                        150
                                                               458
                                                                      450.26 452
401
402
                            obser
                    5
                                          seven
403
       1
             412.81 397.56 365
                                          15
                                                 482.29 480.88 483
404
             477.22 470.71 455
       2
                                          30
                                                 485.63 483.04 488
405
                                          50
       3
             488.28 483.93 480
                                                488.36 484.63 489
406
      4
             489.92 485.99 486
                                          75
                                                488.64 484.35 486
407
       5
                                          100
                                                484.84 480.83 482
             489.74 485.76 485
408
       7
             488.64 484.35 486
                                          150
                                                462.6 462.87 466
409
       10
             486.91 481.61 487
410
             484.27 476.72 473
       15
                                          ten
411
                                                 476.04 474.34 477
       20
             481.93 471.24 468
                                          15
412
                                          30
                                                 480.34 477.22 483
413
       at one meter depth
                                                        50
                                                               484.52 480.02 486
414
                     5
                                          75
                                                 486.91 481.61 487
              1
                            obser
415
              409.46 395.2 375
                                          100
                                                 485.64 480.73 487
       1
416
       2
             470.26 464.23 451
                                          150
                                                 469.59 470.72 465
417
       3
             481.4 477.44 473
418
       4
              483.73 480.1 478
                                          fifteen
       5
419
             484.34 480.76 481
                                          15
                                                 465.86 463.44 462
420
       7
              484.84 480.83 482
                                          30
                                                 471.16 467.33 464
421
             485.64 480.73 487
                                          50
       10
                                                 478.37 471.97 468
422
       15
             487.13 480.11 476
                                          75
                                                 484.27 476.72 473
423
       20
             488.92 478.96 476
                                          100
                                                 487.13 480.11 476
424
                                          150
                                                 481.48 480.11 479
425
426
       at 1.5 meter depth
                                                        twenty
427
                                                455.96 452.55 453
                                          15
              1
                     5
                            obser
428
       1
              448.77 449
                            445
                                          30
                                                 463.47 457.22 456
429
       2
             451.15 451.41 445
                                          50
                                                 472.5 463.46 462
```

430	3	453.44 453.69 453	75	481.93 471.24 468
431	4	455.71 455.98 452	100	488.92 478.96 476
432	5	458 450.26 452	150	493.67 493.95 486
433	7	462.6 462.87 466		
434	10	469.59 470.72 465		
435	15	481.48 480.11 479		
436	20	493.67 493.95 486		

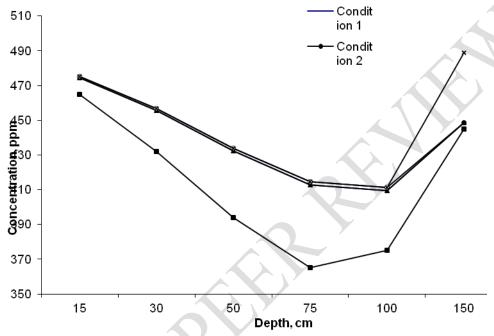


Fig. 16: Performance of model-1 under limiting conditions at different depth on first day

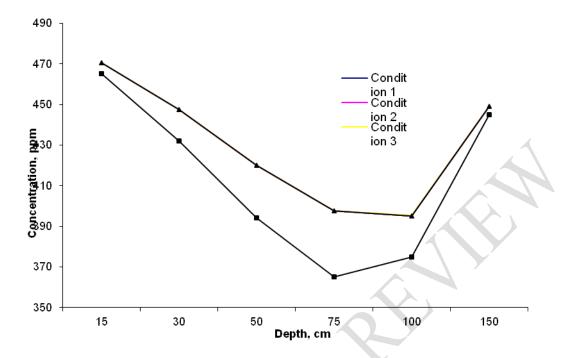


Fig. 17: Performance of model-2 under limiting conditions at different depth on first day